

^{*:} TOLERANCE BETWEEN DOWELS \pm 0.02, BETWEEN SCREW HOLES \pm 0.1

Size Ø	Cylinder bore Ø	Holding moment	Clamping moment (0,5 MPa)	Weight (clamping arm not included)
63 mm	40 mm	1750 Nm	380 Nm	3,8 Kg

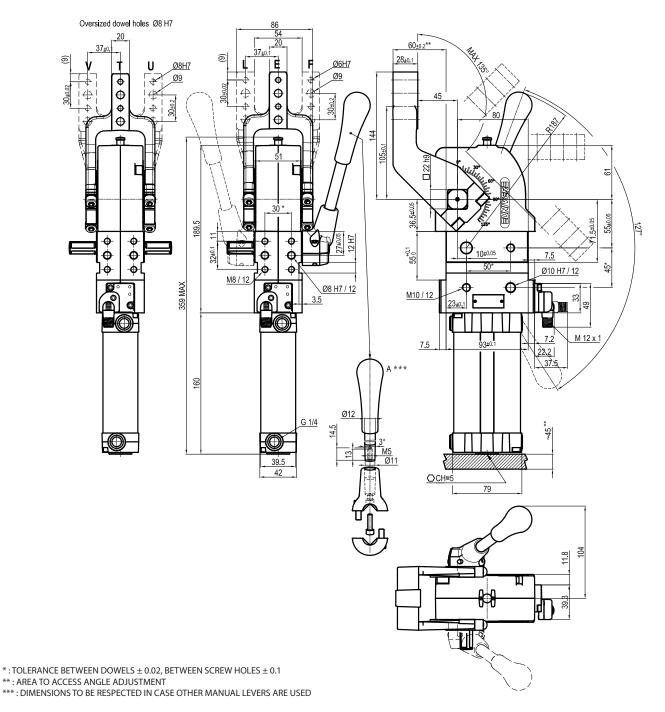
Min./Max. operating pressure: 0,4 / 0,6 MPa Operating temperature: $5^{\circ} \div 45^{\circ} C$ Opening angle: adjustable

Without arm
Electronic sensor with M12 swivel connector, from 0° to 90° Supply voltage: 10 ÷ 30 Vdc IP code: IP 65

^{**:} AREA TO ACCESS ANGLE ADJUSTMENT

^{***:} DIMENSIONS TO BE RESPECTED IN CASE OTHER MANUAL LEVERS ARE USED





UABM63 O K0	6 ARM STYLE	7 ARM TYPE
6 7	E = Central E = Right	A = Aluminium S = Steel

L = Left

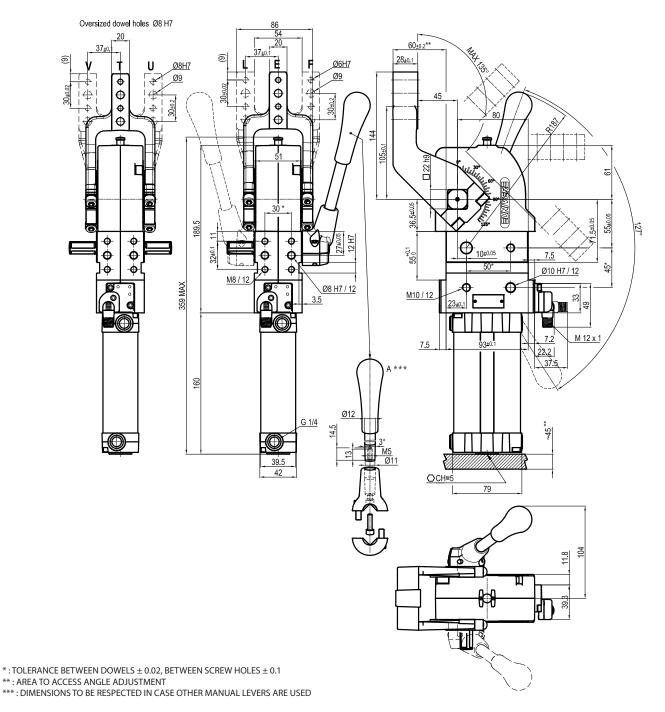
Size Ø	Cylinder bore Ø	Holding moment	Clamping moment (0,5 MPa)	Weight (clamping arm not included)
63 mm	50 mm	1750 Nm	380 Nm	3,8 Kg

Min./Max. operating pressure: 0.4/0,6 MPa Operating temperature: $5^{\circ} \div 45^{\circ}$ C Opening angle: adjustable from 0° to 135° Arm position: 180° With hand lever

With hand lever Electronic sensor with M12 swivel connector, from 0° to 90° Supply voltage: **10 ÷ 30 Vdc**

IP code: **IP 65**





UABM63 O K0	6 ARM STYLE	7 ARM TYPE
6 7	E = Central E = Right	A = Aluminium S = Steel

L = Left

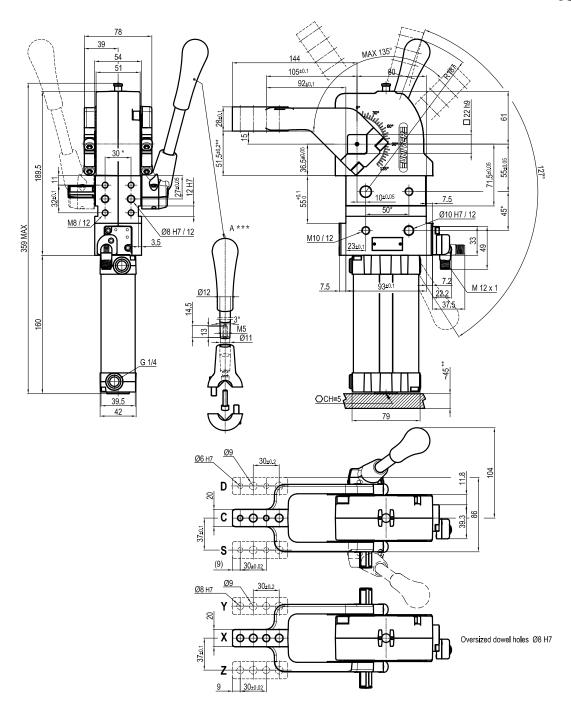
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UABM63 V K0	6 ARM STYLE	7 ARM TYPE	
6 7	C = Central D = Right S = Left	A = Aluminium S = Steel	

Size	Cylinder bore	Holding	Clamping moment	Weight (clamping arm not included)
Ø	Ø	moment	(0,5 MPa)	
63 mm	50 mm	1750 Nm	380 Nm	3,8 Kg

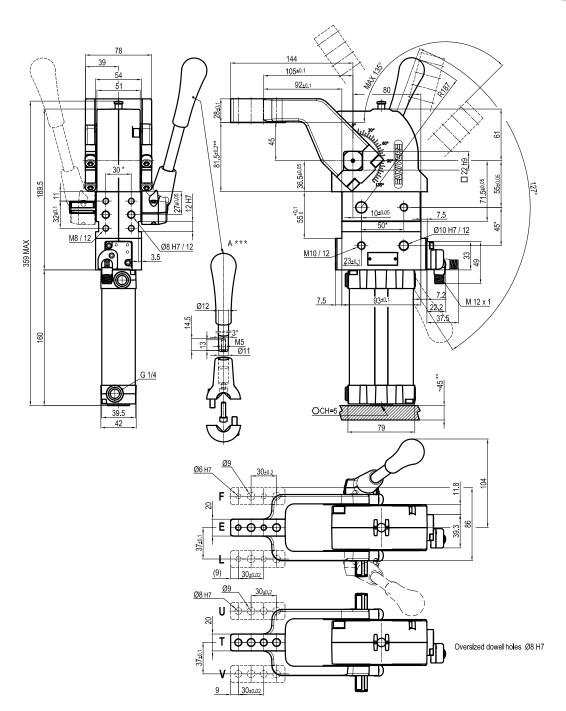
Min./Max. operating pressure: 0,4 / 0,6 MPa Operating temperature: $5^{\circ} \div 45^{\circ} C$ Opening angle: adjustable from 0° to 135° Arm position: 90°

. With hand lever

Electronic sensor with M12 swivel connector, from 0° to 90° Supply voltage: ${\bf 10 \div 30~Vdc}$

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- *** : DIMENSIONS TO BE RESPECTED IN CASE OTHER MANUAL LEVERS ARE USED

UABM63 V K0	6 ARM STYLE	7 ARM TYPE	
6 7	$\mathbf{E} = Central$ $\mathbf{F} = Right$	A = Aluminium S = Steel	
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Electronic sensor with M12 swivel connector, from 0° to 90° Supply voltage: ${\bf 10 \div 30~Vdc}$

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