



MEM520-Bus



MEM540-Bus



MEM620-Bus

# ABSOLUTE ENCODERS MEM-BUS WITH EtherNet/IP™ INTERFACE

Based on the industrial Ethernet communication protocol, **EtherNet/IP™ interface** allows a **steady, flexible and fast** communication between control systems and peripheral devices (such as sensors and actuators). **EtherNet/IP™** networks can effectively integrate multivendor multi-protocol devices to create articulated remote-controlled production systems, a peculiarity which makes it one of the most widespread industrial communication protocols worldwide.



MEM-BUS EtherNet/IP™ encoders offer:

- **High resolution (29 bit)**
- **DLR (Device Level Ring)**
- **IP addressing via hardware and software**
- **Synchronous Real Time transmission**
- **Parameter entering via TCP/IP**
- **Encoder status diagnostic**
- **Position, speed and alarms comprehensive data managed by assembly object 110**

MEM-BUS EtherNet/IP® ENCODER PROFILE	SETTABLE PARAMETERS	STATE INDICATORS
<ul style="list-style-type: none"> <li>• Ref IEC61784-1</li> <li>• Device profile: <b>CIP™ Protocol, encoder profile 22H</b></li> <li>• Physical layer: EtherNet/IP® 100Base-TX, Fast Ethernet, ISO/IEC 8802-3</li> <li>• Output code: Binary</li> <li>• Cycle time ≥ 1 ms • Transmission rate: 100 Mbit/s</li> <li>• Transmission: Cable CAT-5, shielded (STP), ISO/IEC 11801</li> </ul>	via TCP/IP <ul style="list-style-type: none"> <li>• Steps/revolution</li> <li>• Revolutions number</li> <li>• Preset</li> <li>• Rotation direction</li> <li>• Speed unit: steps/s, steps/ms, rev./min.</li> <li>• Position and speed alarm thresholds</li> </ul>	4 two-color signalling LEDs ensure the state diagnostic: <ul style="list-style-type: none"> <li>• LINK 1</li> <li>• LINK 2</li> <li>• Net</li> <li>• Mod</li> </ul>

## PROGRAMMING & OPERATION

**Parameters** are entered via software via **TCP/IP**.

Besides standard **Assembly Objects 1, 2 and 3**, the encoder support the **proprietary object 110**, allowing a comprehensive view of **parameters and alarms relating to speed and position**.

<b>1</b>	It provides the factorized absolute position
<b>2</b>	It provides the factorized absolute position + warnings and allarms
<b>3</b>	It provides the factorized absolute position + 32 bit instant speed
<b>110</b>	It provides the factorized absolute position + 32 bit instant speed + position state record + speed and position warnings

**The speed measuring unit** (step/s, step/ms, RPM), selected in the starting parameter entering phase, *can be modified run-tim*.

**IP addressing** can be entered both by **rotary switches** and **via software (DHCP/BOOTP)**

The function **DLR Device Level Ring** ensures operation even in case of errors or net interruptions.

**CIP Sync™** provides the **increased control coordination** needed for control applications where absolute time synchronization is important to achieve real-time synchronization between distributed intelligent devices and systems.



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## MECHANICAL VERSIONS

MEM620-Bus	MEM520-Bus	MEM540-Bus	MEM440-Bus	MEM450-Bus
Ø 58 mm body 63,5x63,5 mm square flange Ø 31,75 mm centering mask Shaft Ø 6, 8 or 10 mm SIZE25	Ø 58 mm body Ø 58 mm round flange Servo coupling Ø 50 mm centering mask Shaft Ø 6, 8 or 10 mm SYNCHRO FLANGE	Ø 58 mm body Ø 58 mm round flange Ø 36 mm centering mask- 3 holes M4 a 120° on Ø 48 mm Shaft Ø 6, 8 or 10 mm CLAMPING FLANGE	Ø 58 mm body Blind hollow shaft for motor fixing Hollow shaft Ø 8, 10, 12, 14 or 15 mm Antirotational fixing	Ø 58 mm body Blind hollow shaft for motor fixing Hollow shaft Ø 8, 10, 12, 14 or 15 mm Fixing by elastic metal support

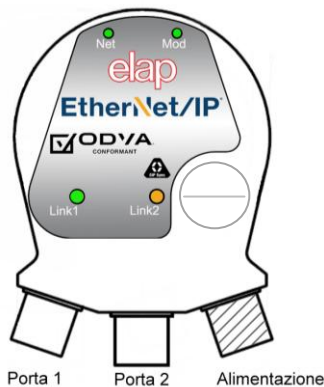
## MECHANICAL & ENVIRONMENTAL SPECIFICATIONS

MEM-Bus	620/520/540	440/450
Materials: housing shaft	Aluminium Stainless steel	
Weight	500 g ca.	
Shaft Ø / Hole Ø	6, 8, 10 mm	6, 8, 10 mm
Revolutions/minute	6000	
Starting torque	≤0.8 Ncm	
Inertia	≤25 g cm <sup>2</sup>	
Max load	80 N axial/100 N radial	
Vibrations resistance (10÷2000 Hz)	100 m/sec <sup>2</sup>	
Shock (11 ms)	50 G	
Protection degree	IP67 – IP65 shaft side	
Operating temperature	-30 ÷ 70°C	
Stocking temperature	-30 ÷ 85°C	

## ELECTRICAL & OPERATING SPECIFICATIONS

Operating principle	Magnetic
Resolution/revolution	8192 steps/rev – 13 bit
Revolutions no. (multiturn)	65536 - 16 bit
Initializing time	< 1 s
Data memory	>20 years No motion – power off
Interface	EtherNet/IP™
Supply	10 ÷ 30 Vdc Protection against polarity reversal
Power consumption	2.5 W
Accuracy	± ½ LSB
Connection	2 M12 female connectors D-coding +1 M12 male connector
Interference immunity	EN 61000-6-2
Emitted interference	EN61000-6-4

## CONNECTIONS



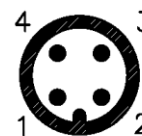
Connector Port1 and Port2  
D-code female M12 connector

Pin	Signal
1	Tx+
2	Rx+
3	Tx-
4	Rx-



Supply connector  
A-code male M12 connector

Pin	Signal
1	+Vsupply (10–30Vdc)
2	N.C.
3	GND (0V)
4	N.C.



Connection by 2 M12 D-coding female connectors + 1 M12 male (supply)

## ORDERING INFORMATION

<b>MEM520B</b>	<b>EIP</b>	<b>M</b>	<b>10</b>
	<b>INTERFACE</b> EIP = EtherNet/IP™	<b>No. of TURNS</b> M = Multiturn	<b>SHAFT Ø / HOLLOW SHAFT Ø</b> 6 – 8 – 10- 12 – 14 – 15 mm

### TYPE

MEM520-Bus = Round flange Ø 58 mm SYNCHRO FLANGE  
MEM540-Bus = Round flange Ø 58 mm CLAMPING FLANGE  
MEM620-Bus = Square flange 63.5x63.5 mm  
MEM440-Bus = Blind hollow shaft for motor coupling  
MEM450-Bus = Blind hollow shaft, fixing by elastic support



CERTIFICATE NO. 11803.01

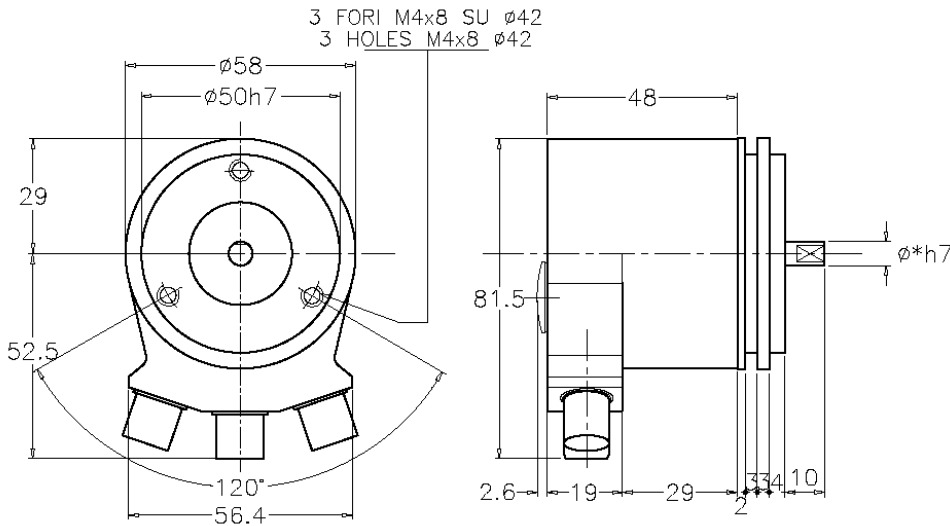


CERTIFICATE NO.E510647

## DIMENSIONS

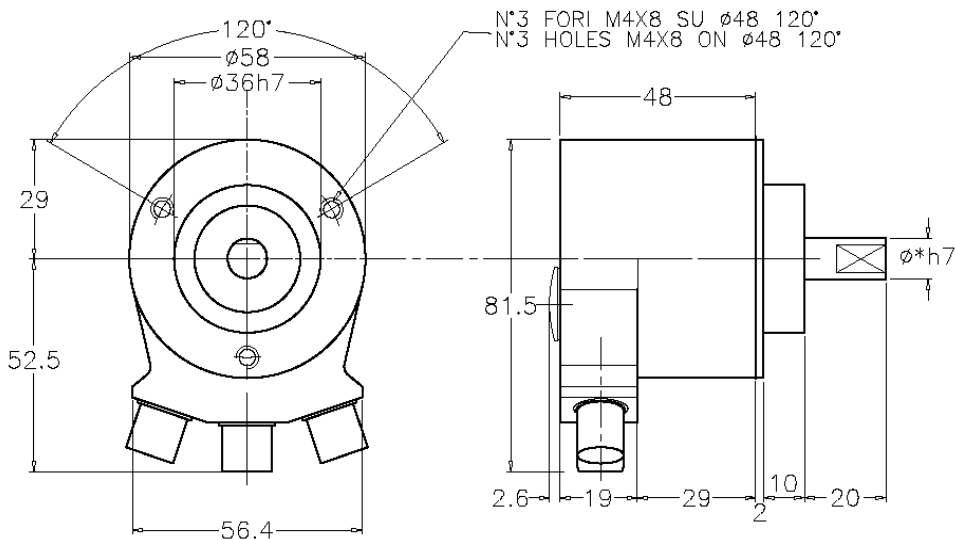
### MEM520-BUS EtherNet/IP™

Ref.M2079



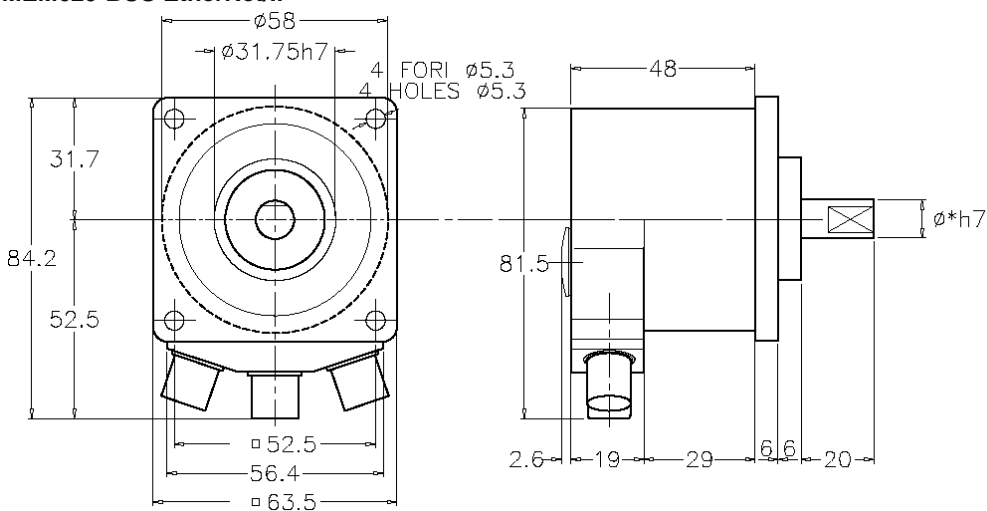
\* AVAILABLE SHAFT DIAMETERS  
8 – 10 length 20mm  
6 length 10mm

### MEM540-BUS EtherNet/IP™



\* AVAILABLE SHAFT DIAMETERS  
8 – 10 length 20mm  
6 length 10mm

### MEM620-BUS EtherNet/IP™



\* AVAILABLE SHAFT DIAMETERS  
8 – 10 length 20mm  
6 length 10mm



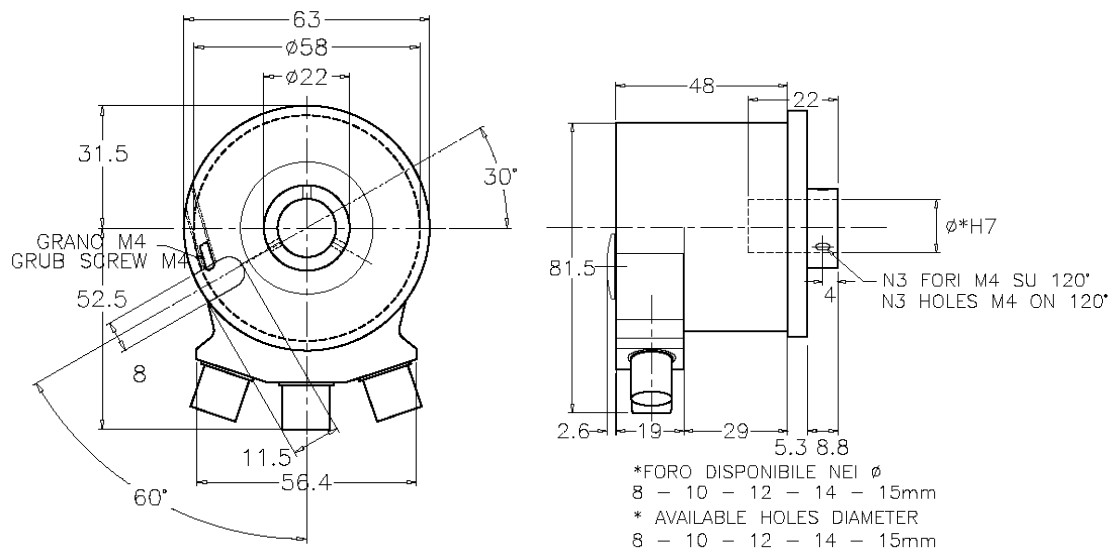
MEM440-Bus



MEM450-Bus

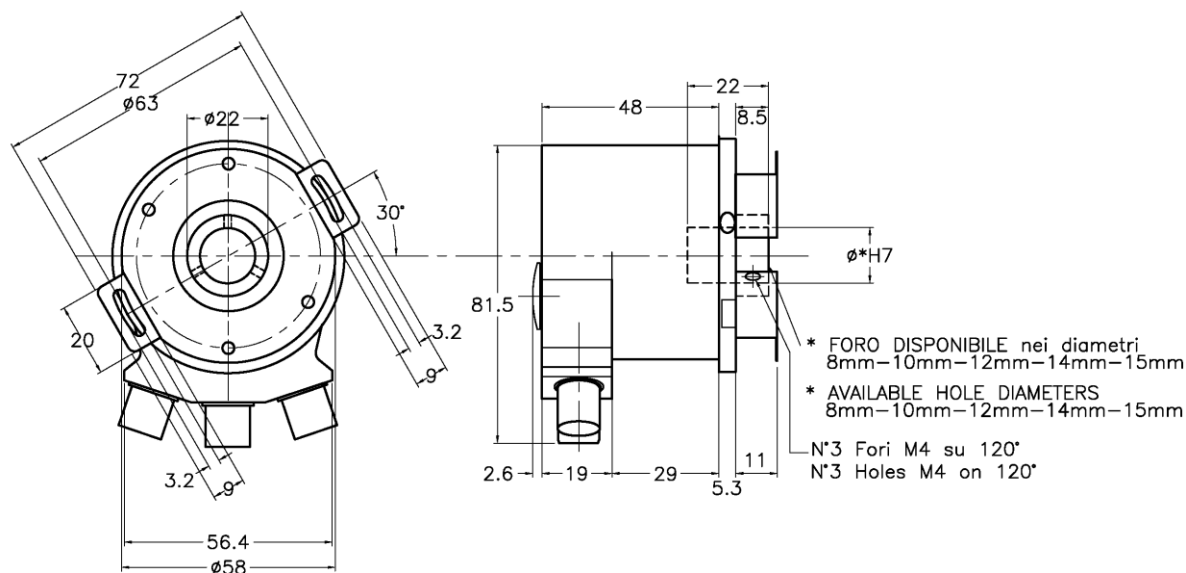
## DIMENSIONS

### MEM440-BUS EtherNet/IP™



Ref.M2079

### MEM450-BUS EtherNet/IP™



Ref.M2080

## REFERENCES

MANUALS, SOFTWARE and DIMENSIONAL DRAWING DOWNLOAD AT:

<https://www.elap.it/absolute-encoders/encoder-mem-bus-ethernet-ip/>



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