



MEM520-Bus



MEM540-Bus



MEM620-Bus

ABSOLUTE ENCODERS WITH EtherCAT[®] INTERFACE

Based on the industrial Ethernet communication protocol, the **EtherCAT[®] interface** is **steady, flexible and fast**, therefore particularly suitable for communication between control systems and peripheral devices, such as I/O systems, drives, sensors and actuators.

MEM-BUS EtherCAT[®] encoders offer:

- *Real Time communication*
- *Flexible number of nodes*
- *Easy installation and maintainance*
- *Flexible net topologies*
- *Automatic slaves addressing*
- *Flexible work ranges progammig*



EtherCAT[®]
Conformance tested

MEM-BUS EtherCAT [®] ENCODER PROFILE	SETTABLE PARAMETERS	STATE INDICATORS
<ul style="list-style-type: none"> • Ref IEC61158-1-6 & IEC61784-2 • Device Profile CANOpen over EtherCAT[®] (CoE), CiA DS-406 • Physical Layer: EtherCAT 100Base-TX, Fast Ethernet, ISO/IEC 8802-3 • Output code: Binary • Cycle time ≥ 1 ms • Transmission rate 100 Mbit/s • Transmission: CAT-5 cable, shielded (STP), ISO/IEC 11801 	<ul style="list-style-type: none"> • Counting direction • Measuring steps per revolution • Total measuring length in steps • Preset value • Speed resolution 	4 signalling LEDs for: <ul style="list-style-type: none"> • L/A in • L/A out • Error • Run

Communication Modes	
MEM-BUS EtherCAT [®] supports different operating modes:	
• Free-Run	The slave application is not synchronized to EtherCAT. The local cycle is started by the local timer interrupt of the application controller. The cycle time can be modified by the Master, but this is a local cycle and it does not depend on communication and on Master cycle.
• SM3 Event	The slave application is synchronized to the SM3 Event (that is the cyclic inputs transmission to the Master). SM events are based on the time an EtherCAT frame is received. This time ca jitter in the range of a few microseconds due to the EtherCAT Master implementation (delay in stack, PHY & MAC delay, etc.).
• SYNC DC	The slave application is synchronized to the SYNC0 event, which is base on the Distributed Clocks Unit (DC). The jitter can be reduced to a few nanoseconds. The DC mode grants high real-time performances

MECHANICAL VERSIONS				
MEM620-Bus	MEM520-Bus	MEM540-Bus	MEM440-Bus	MEM450-Bus
Ø 58 mm body 63,5x63,5 mm square flange • Ø 31,75 mm centering mask Shaft Ø 6, 8 or 10 mm SIZE25	Ø 58 mm body Ø 58 mm round flange Ø 50 mm centeing mask Servo coupling Shaft Ø 6, 8 or 10 mm Synchro Flange	Ø 58 mm body Ø 58 mm round flange Ø 36 mm centering mask • 3 holes M4 a 120° on Ø 48 mm Shaft Ø 6, 8 or 10 mm Clamping flange	Ø 58 mm body Blind hollow shaft for motor fixing Hollow shaft Ø 8, 10, 12, 14 or 15 mm Antirotational fixing	Ø 58 mm body Blind hollow shaft for motor fixing Hollow shaft Ø 8, 10, 12, 14 or 15 mm Fixing by elastic metal support



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MEM440-Bus



MEM450-Bus



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MECHANICAL & ENVIRONMENTAL SPECIFICATIONS			ELECTRICAL & OPERATING SPECIFICATIONS	
MEM-Bus	620/520/540	440/450		
• Materials: case shaft	Aluminium Stainless steel		• Operating principle	Magnetic
• Weight	500 g ca.		• Resolution/revolution	8192 steps/rev – 13 bit
• Shaft/Hollow shaft Ø	6, 8, 10 mm	8, 10, 12, 14, 15 mm	• Revolutions no. (multiturn)	65536 - 16 bit
• Revolutions/minute	6000		• Initializing time	< 1 s
• Starting torque	≤0.8 Ncm		• Data memory	>20 years No motion – power off
• Inertia	≤25 g cm ²		• Interface	EtherCAT®
• Max load	80 N axial/100 N radial		• Supply	10 ÷ 30 Vdc Protection against polarity reversal
• Vibrations resistance (10÷2000 Hz)	100 m/sec ²		• Power consumption	2 W
• Shock (11 ms)	50 G		• Accuracy	± ½ LSB
• Protection degree	IP67 – IP65 shaft side		• Connection	2 M12 female connectors +1 M12 male connector
• Operating temperature	-30 ÷ 70°C		• Interference immunity	EN 61000-6-2
• Stocking temperature	-30 ÷ 85°C		• Emitted interference	EN61000-6-4

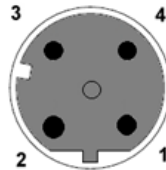
CONNECTIONS



Connectors and LEDs position

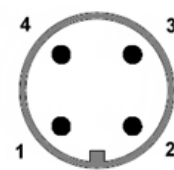
Connectors IN and OUT M12 female type, D code

Pin	Signal
1	Tx +
2	Rx +
3	Tx -
4	Rx -



SUPPLY CONNECTOR M12 male type, A code

Pin	Signal
1	Supply voltage (10-30 V DC)
2	N.C.
3	GND (0V)
4	N.C.



ORDERING INFORMATION

MEM520B

ECT

M

10

A

CONNECTORS POSITION

- = Radial outlet
A = Axial outlet

SHAFT/HOLLOW SHAFT Ø
6 – 8 – 10- 12 – 14 – 15 mm

No. of TURNS
M = Multiturn

INTERFACE
ECT = EtherCAT®

TYPE

- MEM520-B = Round flange Ø 58 mm
- MEM540-B = Round flange Ø 58 mm
- MEM620-B = Square flange 63.5x63.5 mm
- MEM440-B = Blind hollow shaft for motor coupling
- MEM450-B = Blind hollow shaft, fixing by elastic support

EtherCAT®
Conformance tested

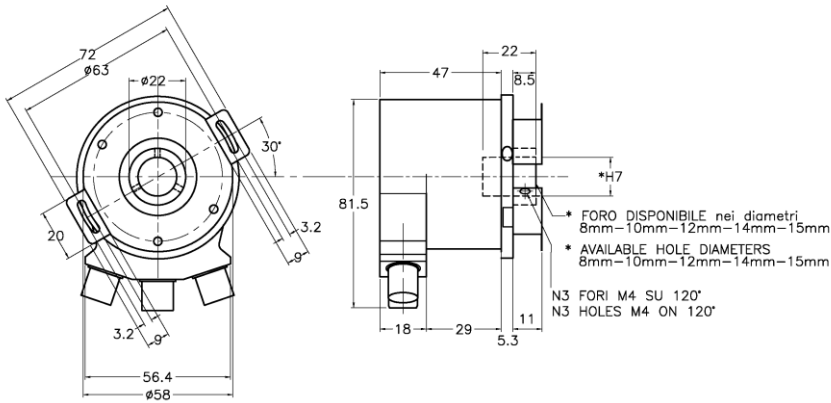
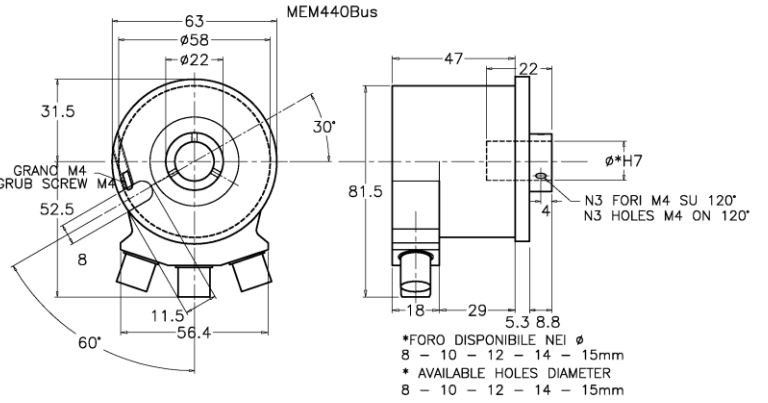
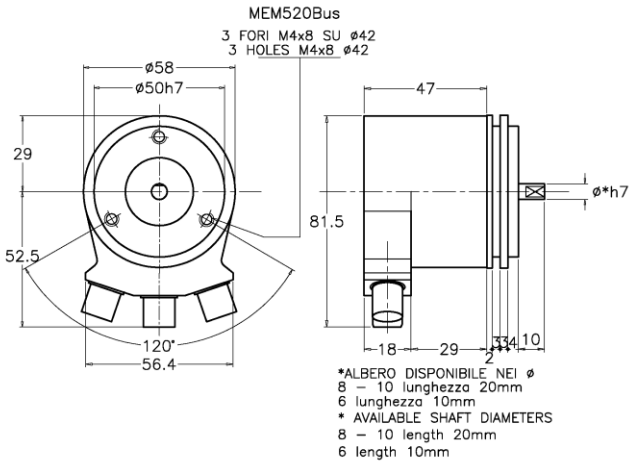
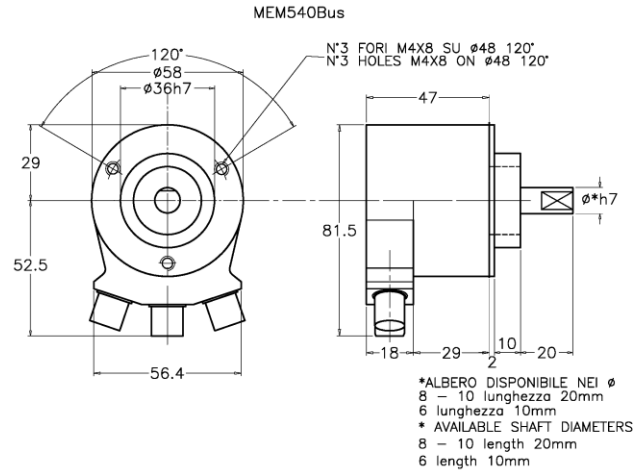
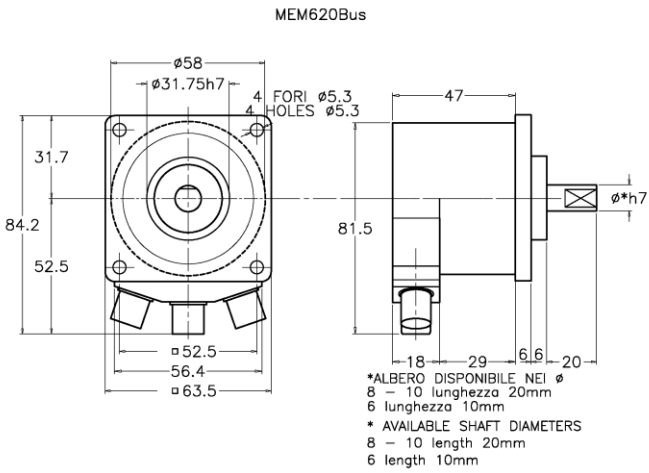


CERTIFICATE NO.E510647
UL listed versions available

DIMENSIONS

MEM-BUS EtherCAT – Radial Connectors

Ref.M1551B

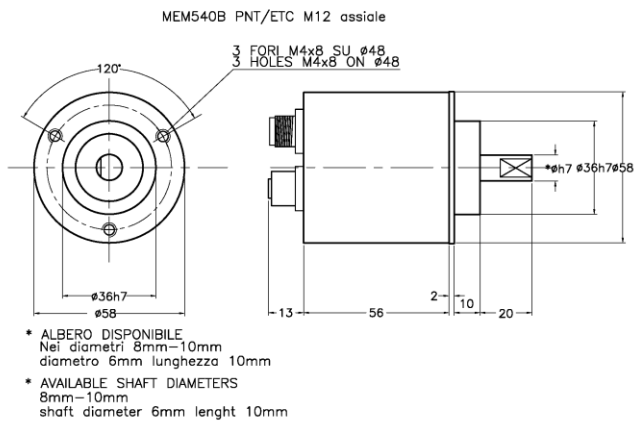
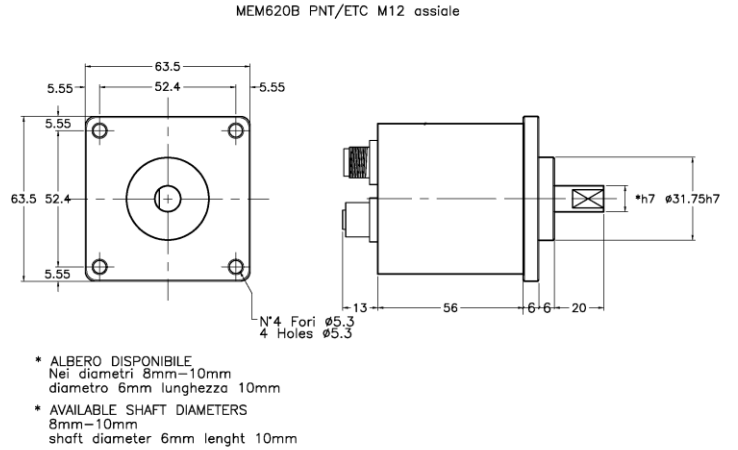
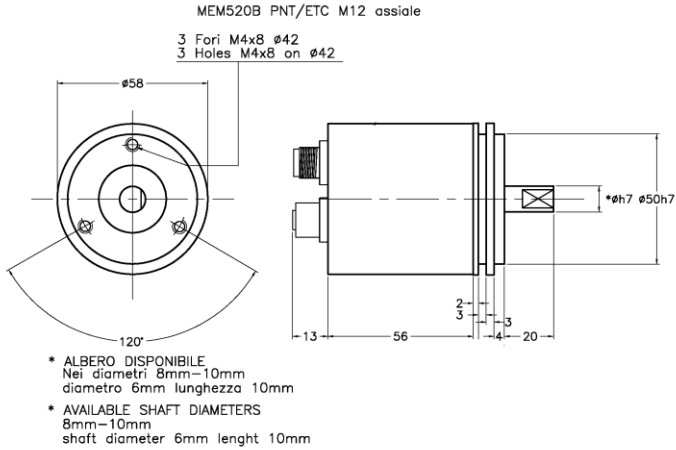


Ref.M1553

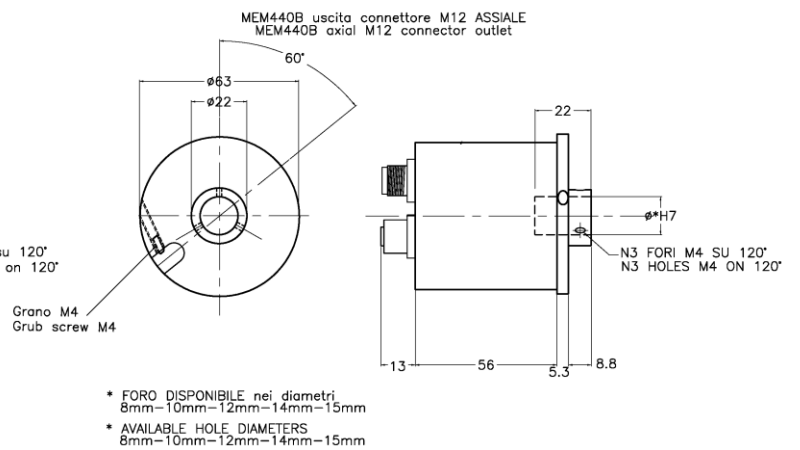
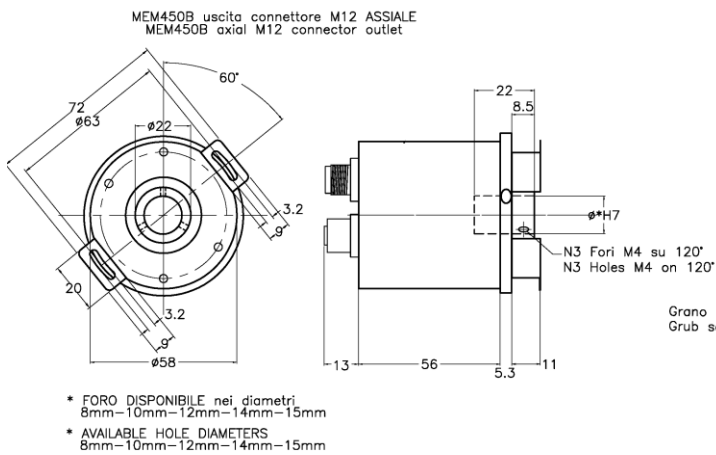


DIMENSIONS

MEM-BUS EtherCAT – Axial Connectors



Ref.M2103



Ref.M2108

REFERENCES

MANUALS, SOFTWARE and DIMENSIONAL DRAWINGS can be downloaded at:

<https://www.elap.it/absolute-encoders/encoder-mem-bus-ethercat/>



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