

ORIENTAL MOTOR U.S.A. Corp. 570 Alaska Avenue Torrance, CA 90503 1-800-GO-VEXTA (468-3982)

#### Item # EH4-AZAKH, Electric Gripper



The EH Series is a electric gripper based on a rack-and-pinion mechanism equipped with an AZ Series motor. Its delicate grip, like that of a human hand, assists in automation and labor-saving.

- Requires AZ Series DC Input Driver
- Connection Cables sold separately

Web Price

\$835.00

#### Specifications | Dimensions | Performance | System

	-
Contact your local sales office for product lead-times, available to ship dates and shipping methods.	
46 mm	
DC	
25 N	
±0.02	
0.1 mm (each side)	
25 mm (12.5 mm each side)	
156 mm/s (78 mm/s each side)	
20 m/s <sup>2</sup> (10 m/s <sup>2</sup> each side)	
20 mm/s (10 mm/s each side)	
	to ship dates and shipping methods.  46 mm  DC  25 N  ±0.02  0.1 mm (each side)  25 mm (12.5 mm each side)  156 mm/s (78 mm/s each side)  20 m/s² (10 m/s² each side)

Minimum Travel Amount	0.02 mm (0.01 mm each side)
Permissible Load	5 N
Static Permissible Moment Load	M <sub>P</sub> : 1.2 N·m M <sub>Y</sub> : 0.12 N·m M <sub>R</sub> : 0.4 N·m
Insulation Class	Class B [130°C (266°F)
Insulation Resistance	100 $M\Omega$ or more when 500 VDC megger is applied between the following places: Case - Motor and sensor windings
Dielectric Strength	Sufficient to withstand the following for 1 minute: Case - Motor and sensor windings 0.5 kVAC 50 Hz or 60 Hz
Ambient Temperature	0 ~ 40°C (32 ~ 104°F) (non-freezing)
Ambient Humidity	85% or less (Non-condensing)
Operating Atmosphere	Use in an area without corrosive gases and dust. The product should not be exposed to water, oil or other liquids.

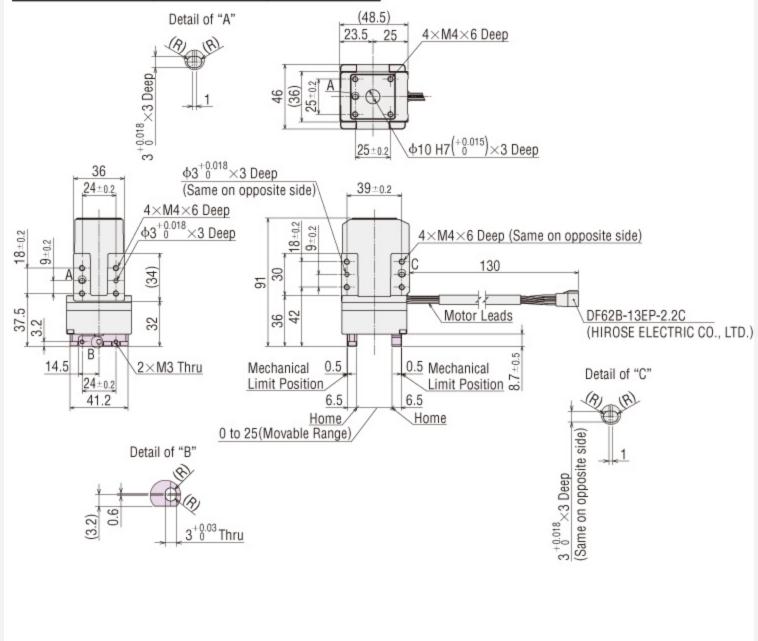
Dimensions

# Dimensions (Unit: mm)

The [

#### 2D & 3D CAD

Product Name	Mass kg	2D CAD
EH4-AZAKH	0.38	D7903



Performance -

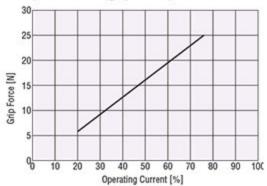
shaded areas are moving parts.

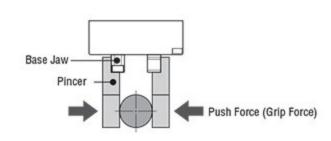
### ■Relationship between Push Force (Grip Force) and Current

The gripping movement of the electric gripper depends on the push-motion operation. The push force (grip force) is s current of the motor.

#### Actual Push Force (Grip Force)

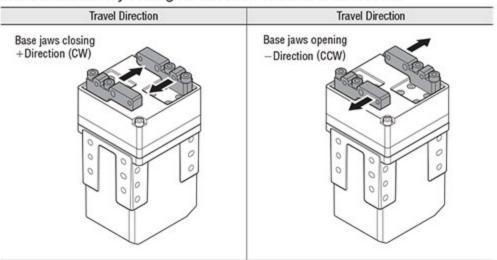
The push force (grip force) and current values are shown below as a reference. Check it on the actual assembled equi





### ■Travel Direction

The default factory setting for direction of travel is as follows:



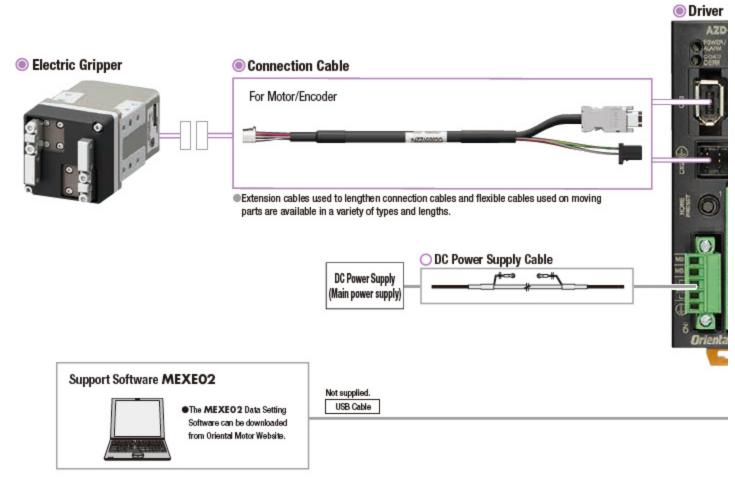
System

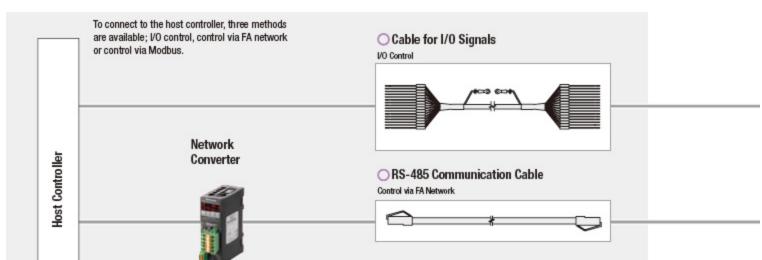
### System Configuration

Combination of Electric Gripper and Built-in Controller Type Driver, or Pulse Input Type Driver with An example of a configuration using I/O control or RS-485 communication is shown below.

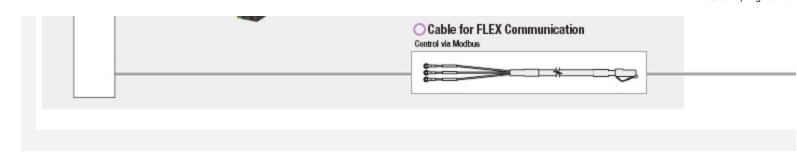
Electric gripper, driver, and a connection cable/flexible connection cable are ordered separately.

- For a pulse input type driver system configuration, please see the Oriental Motor website.
  - Required for operation
  - Optional accessory





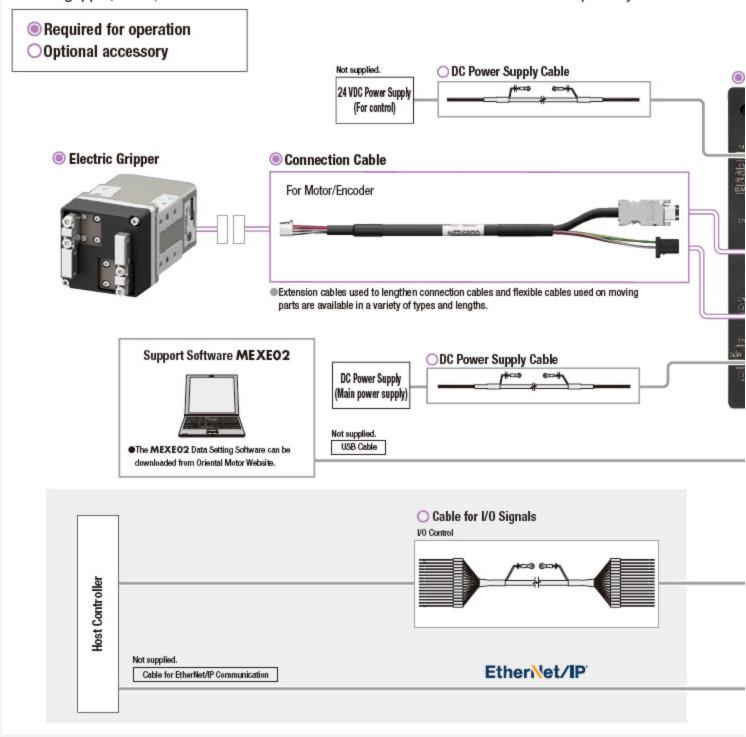
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## System Configuration

### Combination of Electric Gripper and Network Compatible Driver

An example of a configuration using I/O control with an EtherNet/IP-compatible driver or EtherNet/IP is shown be Electric gripper, driver, and a connection cable/flexible connection cable are ordered separately.



<sup>&</sup>lt;sup>1</sup> Quoted Ship Date for orders placed before 12:00 pm PST. Quantities may affect Shipping Date.

Site Search...

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